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# **Formal Verification**

- Verification techniques comprise
- a modelling framework
  M, Γ

to describe a system

a specification language

to describe the properties to be verified

**a verification method**  $M \vDash \phi, \Gamma \vdash \phi$ 

to establish whether a model satisfies a property



# **Transition Systems**

- A very general modelling framework
- Intuitively: a system evolves from one state to another under the action of a transition





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### Example: an assignment

#### States: s:Var -> Val



where s'=s[s(x)+1/x] and  
$$f[v/x](y) = \begin{cases} f(y) & \text{if } x \neq y \\ v & \text{if } x = y \end{cases}$$



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# Example: a digicode

#### 3 keys: A, B, C

#### The door open when ABA is keyed





### Digicode's executions





# A few definitions

- Transition system: <S,L,→>
  - □S set of states
  - L set of transition labels
  - $\Box \rightarrow \subseteq SxLxS$  transition relation
- Path: a sequence π of infinite transitions which follow each other

For example

$$3 \xrightarrow{B} 1 \xrightarrow{A} 2 \xrightarrow{A} 2 \dots$$

is a path of the digicode



# Adding data

- Real-life systems consist of control and data. We can model them by
  - control = states+transitions
  - $\Box$  data = state variables
- A transition system interact with state variables in two ways
  - □ guards a transition cannot occur if the

condition does not holds

assignment a transition can modify the value of some state variables



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# Back to the digicode

We do not tolerate more than 3 mistakes (recorded by the variable m)



# Unfolding

From a theoretical point of view, transition systems with state variables are not strictly necessary, as we can unfold them into ordinary transition systems.

- □ The new states correspond to the old ones + a component for each variable giving its value
- no more guards and assignment on the new transitions



# Unfolding: example



# **Composing systems**

- Systems often consists of cooperating subsystems. Next we describe how to obtain a global transition system form its subsystem by having them cooperate
- There are many ways to cooperate:
  - □ product (no interaction)
  - synchronous product
    - by message passing
    - by asynchronous channels
    - by shared variables



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# Product

- Subsystems do not interact with each other
- The resulting transition system <S,L,→> is the cartesian product of the transition systems <S1,L1,→> ,..., <Sn,Ln,→> representing the subsystems
  - $\Box S = S1 x \dots xSn$
  - $\Box$ L = L1 x ... x Ln
  - $\Box < s_1, \dots, s_n \stackrel{s_1, \dots, e_n \geq}{\longrightarrow} t_1, \dots, t_n > \text{ if for all } i, s_i \stackrel{e_i}{\longrightarrow} t_i$



### Example

#### Few transitions of the product of two modulo 3 counters





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# Synchronized Product

- Subsystems interact by doing some step together (synchronization).
- To synchronize subsystems we restrict the transitions allowed in their cartesian product.
- A synchronization set

 $Sync \subseteq L1 x \dots x Ln$ 

define the labels of those transitions corresponding to a synchronization. Transitions with other labels are forbidden.



## Example

Few transitions of two counters counting at the same time



# Example

Few transitions of two counters counting one at the time

![](_page_16_Figure_2.jpeg)

![](_page_16_Picture_3.jpeg)

# Message Passing

- A special case of synchronized product
- Two special sets of labels
  - □!m emission of message m
  - □?m reception of message m

In message passing, only transitions in which a given emission is executed simultaneously with the corresponding reception will be permitted

![](_page_17_Picture_6.jpeg)

- An elevator in a three floors building consists of
  - $\Box \, a \, cabin$  which goes up and down
  - □ three doors which open an close
  - □ a controller which commands the three doors and the cabin
- Elevator requests from people at one of the three floors are not modeled, as they are the environment outside the system

![](_page_18_Picture_6.jpeg)

![](_page_19_Figure_1.jpeg)

The i-th door

![](_page_19_Figure_3.jpeg)

![](_page_19_Picture_4.jpeg)

![](_page_20_Figure_1.jpeg)

The synchronization

- □Sync =
- {<?open(0),-,-,-,!open(0)>,<?close(0),-,-,-,!close(0)>,
  - <-,?open(1),-,-,!open(1)>,<-,?close(1),-,-,!close(1)>,
- <-,-,?open(2),-,!open(2)>,<-,-,?close(2),-,!close(2)>,
- <-,-,-,?down,!down>,<-,-,?up,!up>}

![](_page_21_Picture_7.jpeg)

# Asynchronous Messages

- Like message passing, but messages are not received instantly.
- Emitted messages but not yet received remain in a communication channel, usually a FIFO buffer
- A communication channel can be modeled by a transition system with a variable (for the buffer content)

![](_page_22_Picture_4.jpeg)

#### Example:

![](_page_23_Figure_1.jpeg)